

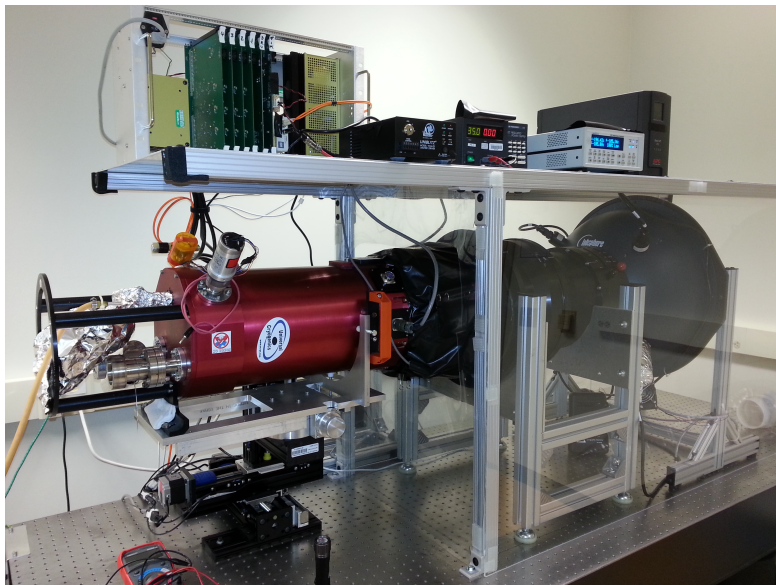
Measurements and Simulations of the Brighter-Fatter Effect

Craig Lage

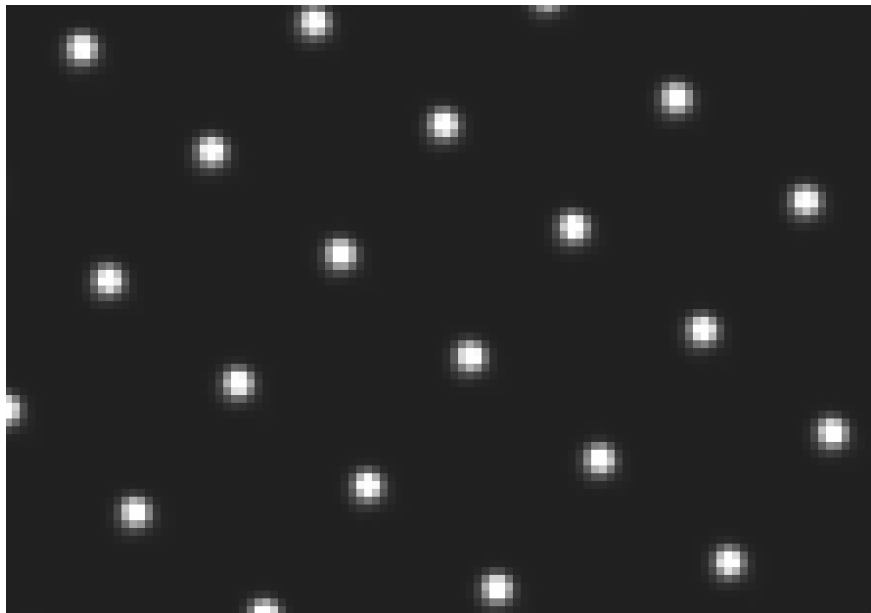
October 23, 2015

- Introduction
- Forward Modeling of Spot images to measure B-F effect.
- Simulations of B-F effect.
- Measurement - Simulation comparison.
- Modeling Stored Charge Self-Consistently
- What are the Free Parameters?
- How to Model Saturation Effects?
- Conclusions and Next Steps

LSST Optical Simulator



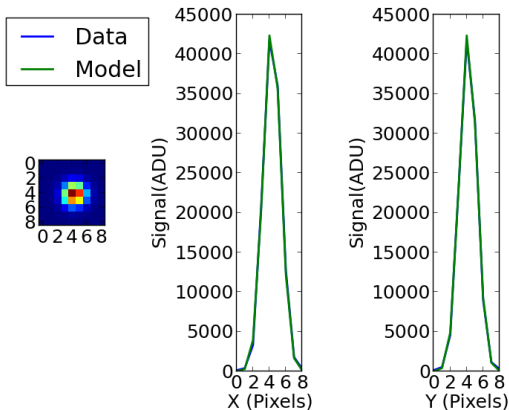
Typical Image of 30 micron Spots



Forward modeling of Discrete Spots

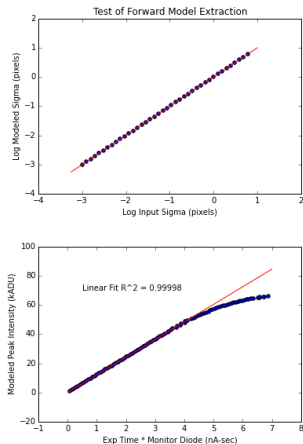
- Use sextractor to identify a list of spots.
 - Typically 1000-2000 in one CCD segment depending on size of window.
 - Use sextractor central pixel location, but not size or exact offset within pixel.
 - Use a constant window (“postage stamp”) for all spots. Using 9x9 pixels.
- Assume all spots have the same shape, but allow variable peak intensity and offset within central spot.
 - Calculate first moment of postage stamp to determine offset within central pixel.
- Assume a 2D Gaussian, calculate expected signal in each pixel
 - $I = I_0(\operatorname{erf}(\frac{x_{\max}}{\sqrt{2}\sigma_x}) - \operatorname{erf}(\frac{x_{\min}}{\sqrt{2}\sigma_x})) * (\operatorname{erf}(\frac{y_{\max}}{\sqrt{2}\sigma_y}) - \operatorname{erf}(\frac{y_{\min}}{\sqrt{2}\sigma_y}))$
 - Find (σ_x, σ_y) which minimizes:
$$\sum_{N_{\text{spots}}} \sum_{x,y} (\text{Measured}_{n,x,y} - \text{Calculated}_{n,x,y})^2$$

Checks on Forward modeling

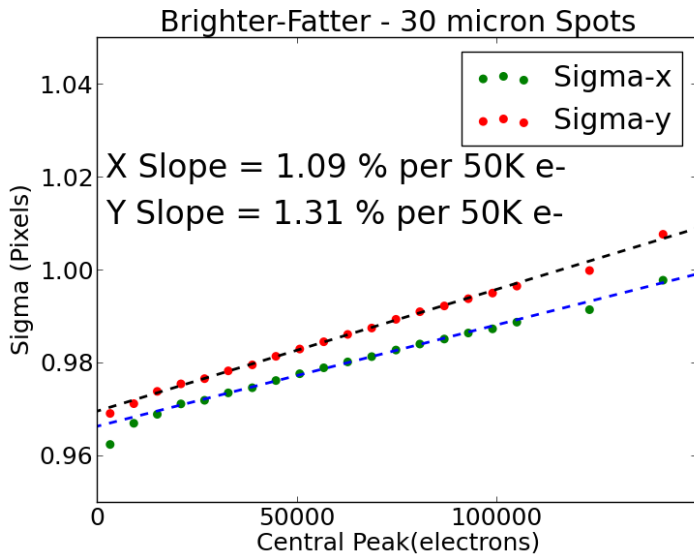


Vertical Scale in ADU.

Multiply by 2.5 for electrons.



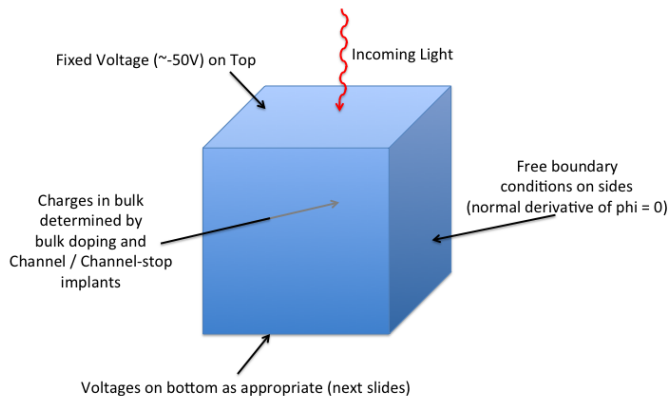
Initial B-F measurements



Simulations of B-F effect.

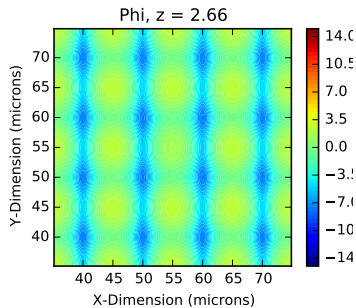
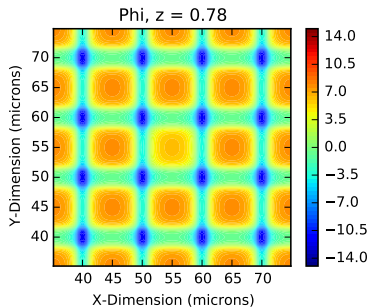
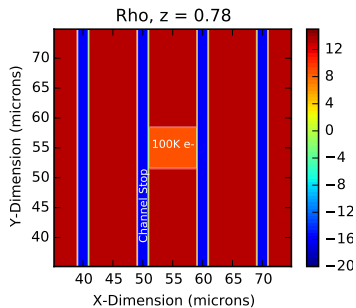
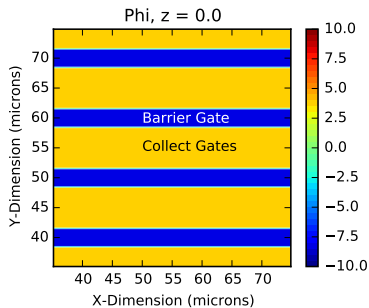
- Brief review of Poisson Solver.
- Diffusion model
- Addition of code to simulate B-F effect.

Typical Simulation 100 μm Cube.



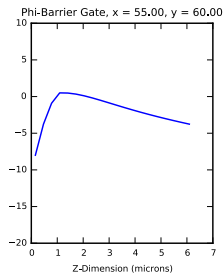
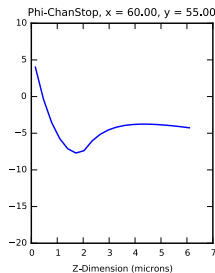
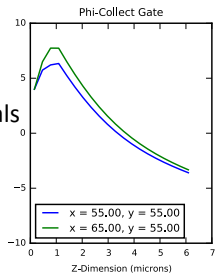
- 100 μm Cube. - 10 X 10 pixels in X and Y.
- 32 grid cells per pixel - cell size = 0.31 μ .

Pixel Array Summary Plot

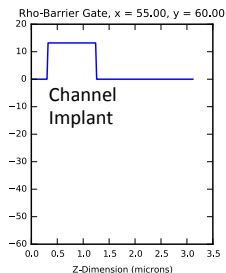
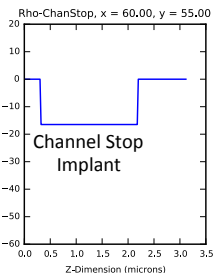
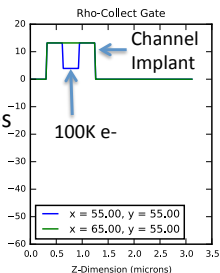


Potentials and Charges - Z-slice at Pixel Center

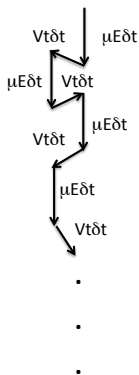
Potentials



Charges

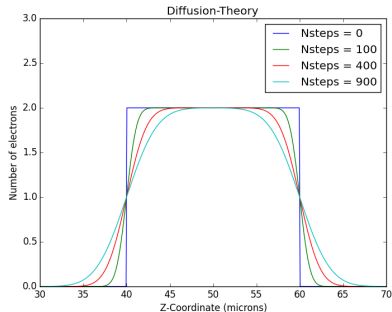
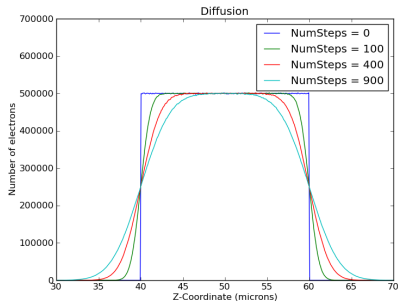


Diffusion Model



- Mobility: $\mu(E, T)$ calculated from Jacobini model
- $\mu = 1584 \frac{\text{cm}^2}{\text{V}\cdot\text{sec}}$ at $E = 6000 \frac{\text{V}}{\text{cm}}$
- Collision time:
 - $\tau = \frac{m_e^*}{q_e} \mu$
 - τ typically about 0.9 ps.
 - δt drawn from exponential distribution with mean of τ
- $V_{th} = \sqrt{\frac{3kT}{2m_e^*}}$
- $V_{th} \approx \mu E$
- Each thermal step in a random direction in 3 dimensions.
- Typically about 1000 steps to propagate to the collecting well.

Diffusion Model Check-out - Step Function

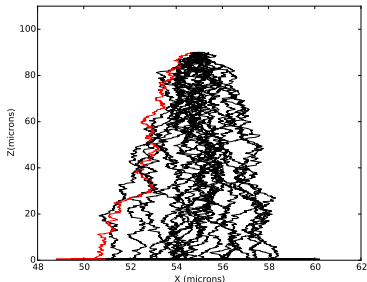


10⁸ electrons in initial step function
- no E-field.

$$\text{erf}\left(\frac{x-x_1}{\sqrt{4D\tau N_{\text{steps}}}}\right) - \text{erf}\left(\frac{x-x_2}{\sqrt{4D\tau N_{\text{steps}}}}\right)$$
$$D = \frac{kT}{q} \mu$$

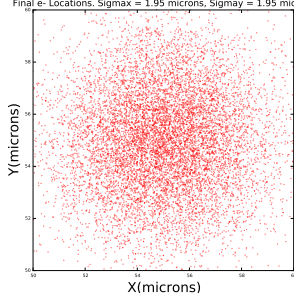
Diffusion Model Check-out - Small (0.1 micron) Spot

Electron Path Plot - Vertical Zoom = 0.1



Electron Paths

CCD Pixel Plots. Grid = 320*320*320.
Final e- Locations. Sigmax = 1.95 microns, Sigmay = 1.95 microns

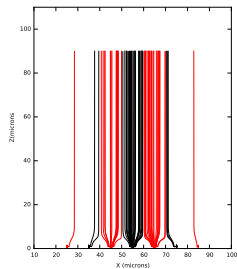
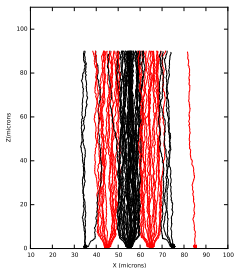
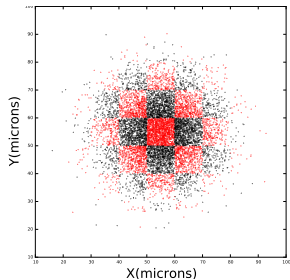
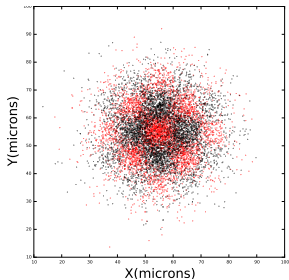


Spot size at collection.

$$\sigma = \sqrt{2 * D * T_{\text{transit}}} = \sqrt{2 * \frac{kT}{q} \mu * \frac{T_{\text{Si}}^2}{\mu V}} = T_{\text{Si}} \sqrt{\frac{2kT}{qV}} = 1.95 \mu$$

FWHM = 4.6 microns, in agreement with Fe measurements.

Impact of electron diffusion



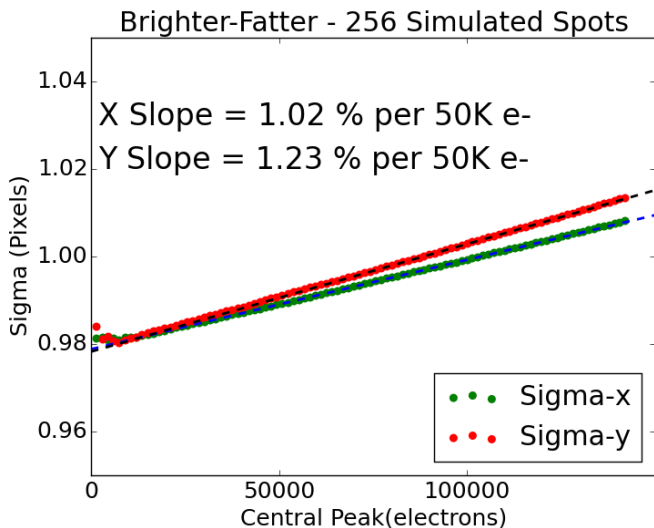
Theoretical Diffusion

Diffusion turned off

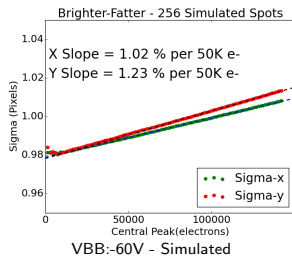
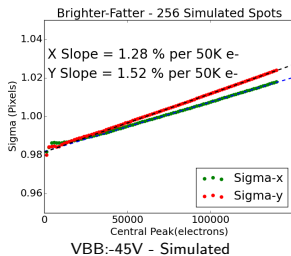
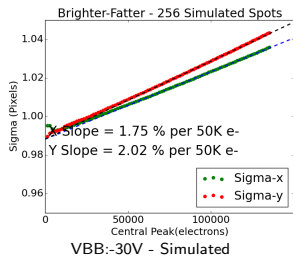
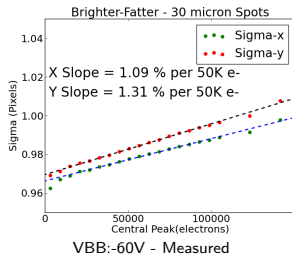
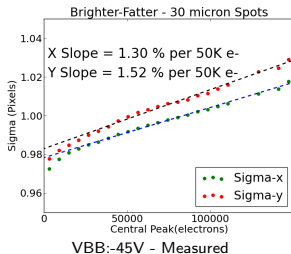
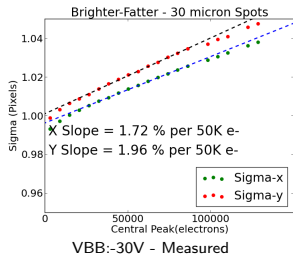
Simulation Strategy for B-F effect.

- Solve Poisson's equation for postage stamp with all pixels empty.
- Choose a random location within the central pixel.
- Determine starting locations for N electrons in a 2D Gaussian spot.
- Propagate these electrons down to their collecting gates.
- Re-solve Poisson's equation with these wells now containing the appropriate charge.
- Repeat with N more electrons.
- I have been using 10,000 electrons per step, which places about 1000 electrons in the central pixel, so about 100 iterations are needed to fill the central pixel.
- In practice, repeat for more than one spot (typical 256), each with a different central location.

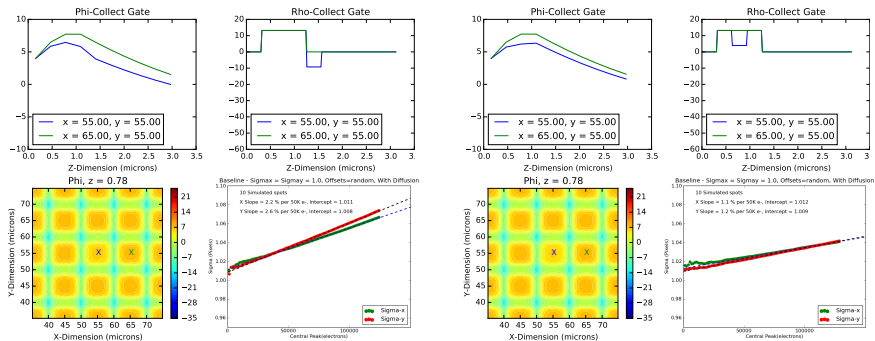
Typical Simulation - 256 Spots - Forward modeled with same code as measurements.



B-F Slopes vs VBB, Measurements and Simulations - Assumed Charge Location



Vertical location of collected charge impacts BF slopes



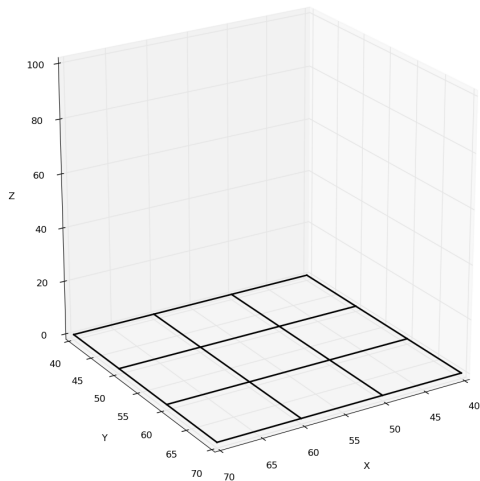
Collected Charge at $z = 1.4 \mu\text{m}$
Slopes = 2.2, 2.6% / 50k e-

Collected Charge at $z = 0.8 \mu\text{m}$
Slopes = 1.1, 1.2% / 50k e-

Self-Consistent Stored Charge Locations

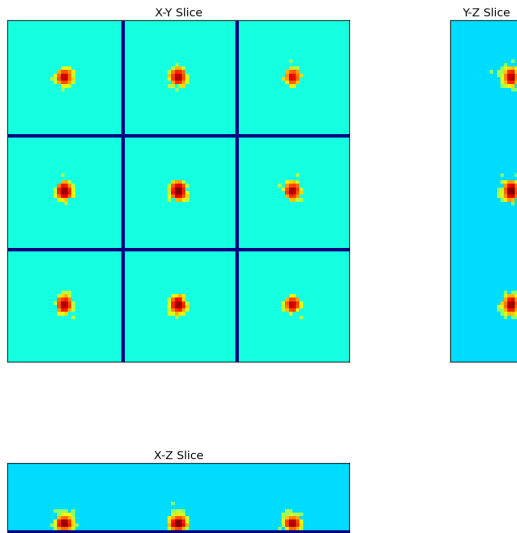
- After propagating electron down to collecting well, we know it's location in three dimensions.
- Continue stepping for some time (100-1000 scattering times) after reaching the collecting well to make sure location has converged.
- Keep this location and use it to calculate the new potentials.

Movie of Pixel Filling - First 10,000 Electrons



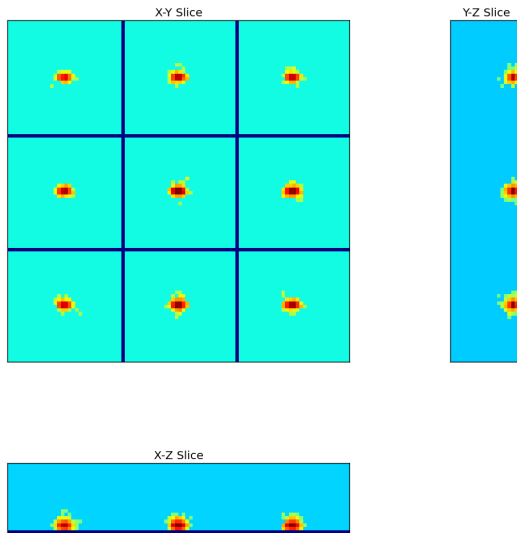
Movie of Pixel Filling - Two Collecting Phases

Well Filling with Two Collecting Phases

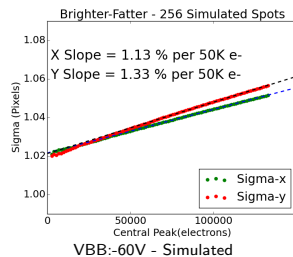
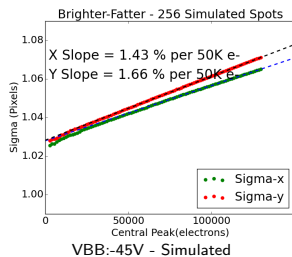
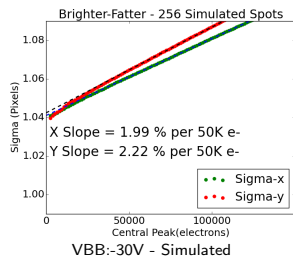
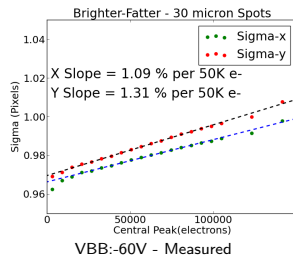
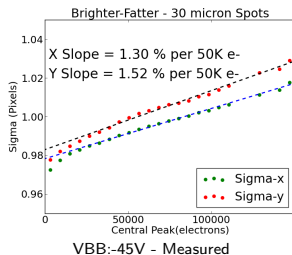
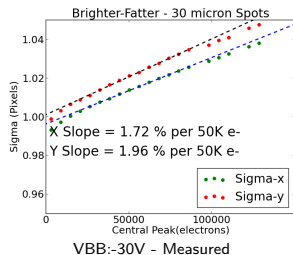


Movie of Pixel Filling - One Collecting Phase

Well Filling with One Collecting Phase

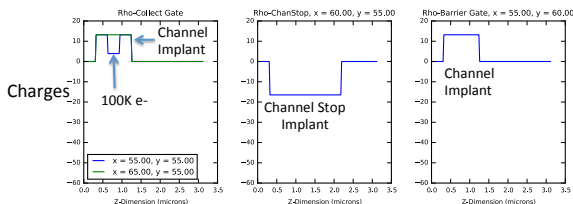


B-F Slopes vs VBB, Measurements and Simulations - Self-Consistent Charge Location

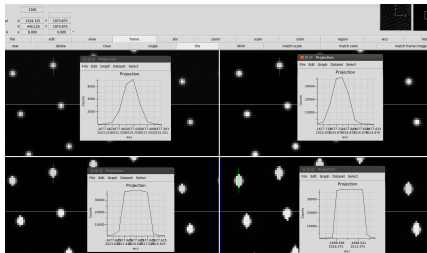


What are the Free Parameters?

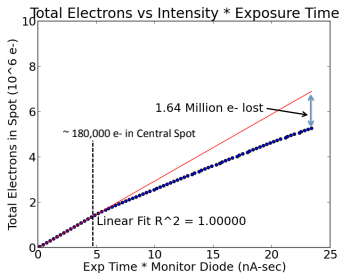
- Diffusion Model:
 - None - Well established Silicon parameters.
- Potentials at Boundaries:
 - None - Applied voltages and geometries are known.
- Charges in Silicon Bulk:
 - Total Charge, Depth, and Profile in Channel region
 - Total Charge, Depth, and Profile in Channel Stop region
 - Is Channel Stop region depleted or are there free holes?
 - Can a device simulator like Silvaco help pin these down?
 - If not, we will tune them in based on CCD measurements.



Measured Saturation Effects

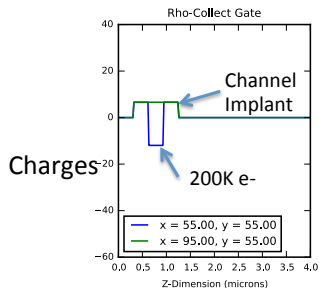
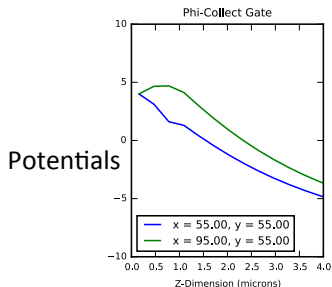


As exposure increases, STA3800 shows saturation at $\approx 180,000$ electrons/pixel.



Electrons not just being re-distributed, but being lost!

Modeling Saturation Effects



- At $\approx 200,000$ electrons, buried channel disappears.
- Potential maximum (where electrons go) contacts the surface.
- Subsequent charge is lost, either through trapping or recombination at the surface.

Performance Benchmark

- NERSC Edison - 1 core
- 360^3 grid - grid cell 0.31μ
- 10,000 electrons

Initialize	Poisson Solution	Calculate E Fields	Trace 10,000 electrons
4 sec.	40 sec.	3 sec.	27 sec.

- So a B-F run with 256 spots, 3 million electrons (300,000 in central spot) takes about 6 hours.

Conclusions and Next Steps

- Conclusions:
 - Simulations are reproducing major aspects of B-F measurements:
 - Magnitude of slopes.
 - Difference between X and Y slopes.
 - Change in slopes with V_{bb} .
 - While there are some free parameters, we should be able to narrow these down with more knowledge of the CCD and more measurements.
 - Use Silvaco to better determine doping profiles?
- Next Steps
 - More measurements and simulations, especially:
 - Improve modeling of saturation effects.
 - One vs Two collecting phases.
 - Impact of parallel gate voltages.
 - Different spot sizes.
 - Get more people using the code:
Latest version (https://github.com/craiglagegit/Poisson_CCD16)

Back-Up Slides

Description of Numerics

Solving Poisson's Equation on a Grid

$$\nabla^2 \varphi = \rho$$

$$\frac{\partial^2 \varphi_{i,j,k}}{\partial x^2} = \frac{(\varphi_{i+1,j,k} - \varphi_{i,j,k}) - (\varphi_{i,j,k} - \varphi_{i-1,j,k})}{h^2}$$

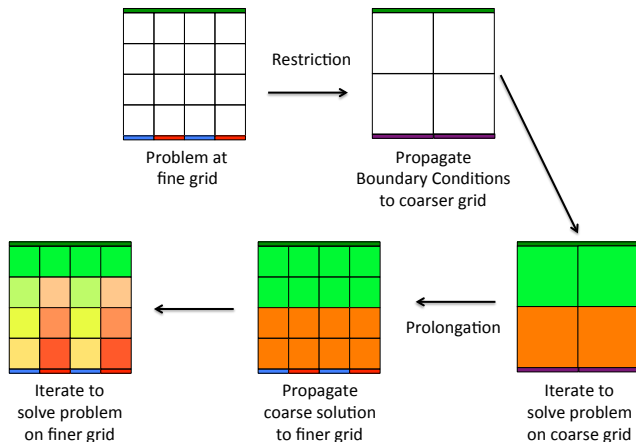
$$(\varphi_{i+1,j,k} + \varphi_{i-1,j,k} + \varphi_{i,j+1,k} + \varphi_{i,j-1,k} + \varphi_{i,j,k+1} + \varphi_{i,j,k-1} - 6 * \varphi_{i,j,k}) = h^2 * \rho_{i,j,k}$$

$$\varphi_{i,j,k} = \frac{1}{6} * (\varphi_{i+1,j,k} + \varphi_{i-1,j,k} + \varphi_{i,j+1,k} + \varphi_{i,j-1,k} + \varphi_{i,j,k+1} + \varphi_{i,j,k-1} - h^2 * \rho_{i,j,k})$$

$$\varphi_{i,j,k}^{(n+1)} = \frac{1}{6} * (\varphi_{i+1,j,k}^{(n)} + \varphi_{i-1,j,k}^{(n)} + \varphi_{i,j+1,k}^{(n)} + \varphi_{i,j-1,k}^{(n)} + \varphi_{i,j,k+1}^{(n)} + \varphi_{i,j,k-1}^{(n)} - h^2 * \rho_{i,j,k})$$

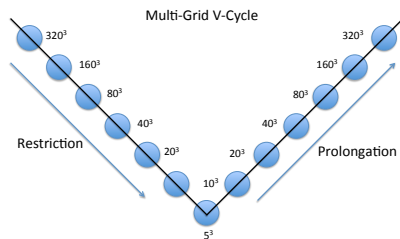
- Conceptually, we simply iterate until convergence.
- In practice, it converges very slowly - millions of iterations are required.

Multi-Grid Methods to the Rescue - I



- Long wavelength modes are determined at the coarse grid.
- Iterations at each finer grid only need to be long enough to determine the short wavelength modes.

Multi-Grid Methods to the Rescue - II



Finest Grid	Cells/Pixel	Grid Spacing	Time (laptop)
160^3	16	0.625 micron	5 sec.
320^3	32	0.3125 micron	40 sec.
640^3	64	0.15625 micron	5 min.

- Each successive step down is ≈ 8 times faster than the next larger grid.
- In practice, I iterate the coarsest grid to machine precision, then 2X fewer iterations at each finer grid, ending with 128 iterations at the finest grid.